

საქართველოს სტანდარტი

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ინტეგრაცია (ისო 10218-2:2011)

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ეროვნული სააგენტო
თბილისი

სსტ ენ ისო 10218-2:2011/2019

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English Version

Robots and robotic devices - Safety requirements for industrial robots - Part 2: Robot systems and integration (ISO 10218-2:2011)

Robots et dispositifs robotiques - Exigences de sécurité pour les robots industriels - Partie 2: Systèmes robots et intégration (ISO 10218-2:2011)

Roboter und Robotikgeräte - Sicherheitsanforderungen - Teil 2: Industrierobotersystem und Integration (ISO 10218-2:2011)

This European Standard was approved by CEN on 21 April 2011.

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Contents

Page

Foreword.....3

Annex ZA (informative) Relationship between this European Standard and the Essential Requirements of EU Directive 2006/42/EC4

საინფორმაციო ნაწილი. სრული ტექსტის სანახავად შეიძინეთ სტანდარტი.

Foreword

This document (EN ISO 10218-2:2011) has been prepared by Technical Committee ISO/TC 184 "Automation systems and integration" in collaboration with Technical Committee CEN/TC 310 "Advanced automation technologies and their applications" the secretariat of which is held by BSI.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by January 2012, and conflicting national standards shall be withdrawn at the latest by January 2012.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN [and/or CENELEC] shall not be held responsible for identifying any or all such patent rights.

This document has been prepared under a mandate given to CEN by the European Commission and the European Free Trade Association, and supports essential requirements of EU Directive.

For relationship with EU Directive, see informative Annex ZA, which is an integral part of this document.

According to the CEN/CENELEC Internal Regulations, the national standards organizations of the following countries are bound to implement this European Standard: Austria, Belgium, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland and the United Kingdom.

Endorsement notice

The text of ISO 10218-2:2011 has been approved by CEN as a EN ISO 10218-2:2011 without any modification.

Annex ZA
(informative)

**Relationship between this European Standard and
the Essential Requirements of EU Directive 2006/42/EC**

This European Standard has been prepared under a mandate given to CEN by the European Commission and the European Free Trade Association to provide a means of conforming to Essential Requirements of the New Approach Directive 2006/42/EC Machinery safety.

Once this standard is cited in the Official Journal of the European Union under that Directive and has been implemented as a national standard in at least one Member State, compliance with the normative clauses of this standard confers, within the limits of the scope of this standard, a presumption of conformity with the relevant Essential Requirements of that Directive and associated EFTA regulations.

WARNING — Other requirements and other EU Directives may be applicable to the product(s) falling within the scope of this standard.

საინფორმაციო ნაწილი. სრული ტექსტის სანახავად შეიძინეთ სტანდარტი.

**Robots and robotic devices — Safety
requirements for industrial robots —**

Part 2:

Robot systems and integration

*Robots et dispositifs robotiques — Exigences de sécurité pour
les robots industriels —*

Partie 2: Systèmes robots et intégration



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Contents

Page

Foreword	iv
Introduction.....	v
1 Scope	1
2 Normative references	1
3 Terms and definitions	2
4 Hazard identification and risk assessment.....	4
4.1 General	4
4.2 Layout design	5
4.3 Risk assessment	6
4.4 Hazard identification	8
4.5 Hazard elimination and risk reduction	9
5 Safety requirements and protective measures	9
5.1 General	9
5.2 Safety-related control system performance (hardware/software).....	9
5.3 Design and installation	10
5.4 Limiting robot motion	14
5.5 Layout.....	16
5.6 Robot system operational mode application.....	17
5.7 Pendants.....	21
5.8 Maintenance and repair	22
5.9 Integrated manufacturing system (IMS) interface.....	23
5.10 Safeguarding.....	24
5.11 Collaborative robot operation	32
5.12 Commissioning of robot systems	35
6 Verification and validation of safety requirements and protective measures	36
6.1 General	36
6.2 Verification and validation methods.....	37
6.3 Required verification and validation	37
6.4 Verification and validation of protective equipment.....	37
7 Information for use	38
7.1 General	38
7.2 Instruction handbook.....	39
7.3 Marking.....	43
Annex A (informative) List of significant hazards	44
Annex B (informative) Relationship of standards related to protective devices.....	47
Annex C (informative) Safeguarding material entry and exit points.....	49
Annex D (informative) Operation of more than one enabling device	52
Annex E (informative) Conceptual applications of collaborative robots	53
Annex F (informative) Process observation.....	55
Annex G (normative) Means of verification of the safety requirements and measures	58
Bibliography.....	71

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 10218-2 was prepared by Technical Committee ISO/TC 184, *Automation systems and integration*, Subcommittee SC 2, *Robots and robotic devices*.

ISO 10218 consists of the following parts, under the general title *Robots and robotic devices — Safety requirements for industrial robots*:

- *Part 1: Robots*
- *Part 2: Robot systems and integration*

საინფორმაციო ნაწილი. სრული ტექსტის სახსრად შეიძლება სტანდარტი.

Introduction

This part of ISO 10218 has been created in recognition of the particular hazards that are presented by industrial robot systems when integrated and installed in industrial robot cells and lines.

Hazards are frequently unique to a particular robot system. The number and types of hazards are directly related to the nature of the automation process and the complexity of the installation.

The risks associated with these hazards vary with the type of robot used and its purpose and the way in which it is installed, programmed, operated, and maintained.

For the purpose of understanding requirements in this part of ISO 10218, a word syntax is used to distinguish absolute requirements from recommended practices or suggested actions. The word “shall” is used to identify requirements necessary for compliance with this part of ISO 10218. Such requirements have to be accomplished unless an alternative instruction is provided or a suitable alternative is determined by a risk assessment. The word “should” is used to identify suggestions, recommended actions or possible solutions for requirements, but alternatives are possible and the suggested actions are not absolute.

In recognition of the variable nature of hazards with the application of industrial robots, this part of ISO 10218 provides guidance for the assurance of safety in the integration and installation of robots. Since safety in the use of industrial robots is influenced by the design of the particular robot system, a supplementary, though equally important, purpose is to provide guidelines for the design, construction and information for use of robot systems and cells. Requirements for the robot portion of the system can be found in ISO 10218-1.

Providing for a safe robot system or cell depends on the cooperation of a variety of “stakeholders” – those entities that share in a responsibility for the ultimate purpose of providing a safe working environment. Stakeholders may be identified as manufacturers, suppliers, integrators and users (the entity responsible for using robots), but all share the common goal of a safe (robot) machine. The requirements in this part of ISO 10218 may be assigned to one of the stakeholders, but overlapping responsibilities can involve multiple stakeholders in the same requirements. While using this part of ISO 10218, the reader is cautioned that all of the requirements identified may apply to them, even if not specifically addressed by “assigned” stakeholder tasks.

This part of ISO 10218 is complementary and in addition to ISO 10218-1, which covers the robot only. This part of ISO 10218 adds additional information in line with ISO 12100 and ISO 11161, International Standards for requirements to identify and respond in a type-C standard to unique hazards presented by the integration, installation and requirements for use of industrial robots. New technical requirements include, but are not limited to, instructions for applying the new requirements in ISO 10218-1 for safety-related control system performance, robot stopping function, enabling device, programme verification, cableless pendant criteria, collaborating robot criteria and updated design for safety.

This part of ISO 10218 and ISO 10218-1 form part of a series of standards dealing with robots and robotic devices. Other standards cover such topics as integrated robotic systems, coordinate systems and axis motions, general characteristics, performance criteria and related testing methods, terminology, and mechanical interfaces. It is noted that these standards are interrelated and also related to other International Standards.

For ease of reading this part of ISO 10218, the words “robot” and “robot system” refer to “industrial robot” and “industrial robot system” as defined in ISO 10218-1.

Figure 1 describes the relationship of the scope of machinery standards used in a robot system. The robot alone is covered by ISO 10218-1, the system and cell is covered by this part of ISO 10218. A robot cell may include other machines subject to their own C level standards, and the robot system can be part of an integrated manufacturing system covered by ISO 11161 which in turn can also make reference to other relevant B and C level standards.

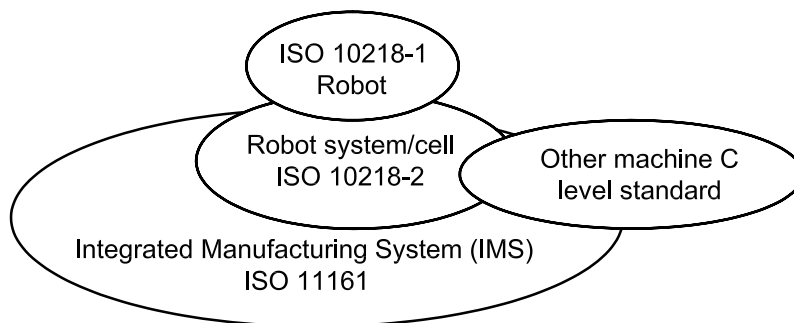


Figure 1 — Graphical view of relationships between standards relating to robot system/cell

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